Two Kinds of Foundations

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Joint work with Guy E. Blelloch and our students, past and present.

Inspiration from LFCS

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Strong emphasis on beauty in theory and practice.

- Elegant mathematical theories (domains, logics, models).
- Elegant programming languages (HOPE, ML).
- Elegant verification tools (LEGO, CWB).

Two Sources of Beauty

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- Logical: compositionality (human effort).
- Combinatorial: efficiency (machine effort).

But these are largely disparate communities, both in the US and in Europe.

Reconciling the Two Theories

Historically,

- The logical side neglects efficiency in favor of structure.
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Prospectively,

- The logical side should pay more attention to efficiency.
- The combinatorial side should pay more attention to structure.

The Great Rift

"On the fact that the Atlantic Ocean has two sides." [EWD]

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- Efficient algorithms for a broad range of problems.
- Language design and verification tools.

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Yet these two "theories" operate largely in isolation!

American Theory

Algorithm analysis is based on machine models:

- Turing machine (TM) or Random Access Machine (RAM).
- Low-level: no abstraction, no composition.
- Allegedly, close to the hardware.

Machine models provide natural complexity measures:

- Time = number of instructions.
- Space = tape or memory usage.

Asymptotics smoothes over differences among models.

American Theory

In practice algorithms are described using C-like notation.

- Clearer than TM or RAM code.
- Analyze compiled code, rather than source code.

An improvement, but still very limited:

- ephemeral data structures.
- manual memory management.
- poor composability.
- no abstraction.

Euro Theory

Euro theory is based on language models:

- Church's (typed and untyped) λ -calculus.
- High-level: abstraction, composition are fundamental.
- Platform-independent.

Language models support composition via variables:

- If ϕ true $\vdash \psi$ true, then if ϕ true, then ψ true.
- If $x : \sigma \vdash N : \tau$, then if $M : \sigma$, then $[M/x]N : \tau$.

The λ -calculus is an elegant theory of composition.

Euro Theory

Languages based on λ -calculus stress

- persistent data structures.
- automatic memory management.
- strong composability.
- abstract types.

But there is relatively little emphasis on efficiency.

- No clear complexity measures.
- Few analytic results (but see Okasaki's CMU Ph.D.).

Thesis

Traditional imperative methods of programming are obsolete.

- Tedious to program, a nightmare to maintain.
- Largely incompatible with parallelism.

Functional methods are destined to dominate.

- Support verification and composition.
- Naturally accommodate parallelism.

The way forward is to synthesize Euro- and American theory.

Cost Semantics

To elevate the level of discourse we require a cost semantics.

- Define the abstract cost of execution of a language.
- Defines the parallel and sequential complexity.

Algorithm analysis is conducted at the level of the code we write.

- Cost semantics assigns a measure to each execution.
- Analyze asymptotic complexity in terms of this measure.

Cost Semantics

The abstract cost is validated by a bounded implementation.

- Transform abstract cost into concrete cost on a machine.
- Account for platform characteristics such as number of processors, cache hierarchy, and interconnect.

An end-to-end asymptotics with a clear separation of concerns.

- High-level, composable development and reasoning.
- Low-level implementation on hardware platforms.

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So simple we teach it to first-year undergraduates!

Cost Semantics for Time

Associate a cost graph to the evaluation of a program.

- Dynamic, fully accurate record of data dependencies.
- Not a static analysis or an approximation!

Example: function application.

$$\frac{e_1 \Downarrow \lambda x.e \ e_2 \Downarrow \ v_2 \ [v_2/x]e \Downarrow \ v}{e_1(e_2) \Downarrow \ v}$$

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$$\frac{e_1 \Downarrow^{g_1} \lambda x.e}{e_1(e_2) \Downarrow^{(g_1 \otimes g_2) \oplus 1 \oplus g} v} \frac{[v_2/x]e \Downarrow^g v}{e_1(e_2) \Downarrow^{(g_1 \otimes g_2) \oplus 1 \oplus g} v}$$

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Application cost $(g_1 \otimes g_2) \oplus \mathbf{1} \oplus g$ specifies that

• Function and argument are evaluated in parallel.

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- Function execution depends on the function and argument.



Work and Span

The work w(g) of a cost graph g is the size of g.

- w(1) = 1, $w(g_1 \otimes g_2) = w(g_1 \oplus g_2) = w(g_1) + w(g_2)$.
- Measures the sequential time complexity.

The span d(g) of a cost graph g is the critical path length of g.

•
$$d(1) = 1$$
, $d(g_1 \otimes g_2) = \max(d(g_1), d(g_2))$,
 $d(g_1 \oplus g_2) = d(g_1) + d(g_2)$.

• Measures the parallel time complexity.



Work = 11, Span =
$$6$$

Mergesort

```
fun merge xs ys =
  case (xs, ys) of
     ([], ys) \Rightarrow ys
  |(xs, []) \Rightarrow xs
  | (x::xs', y::ys') \Rightarrow
    case x<y of
       true \Rightarrow x :: merge xs' ys
     | false \Rightarrow y :: merge xs ys'
fun sort [] = []
  | sort [x] = [x]
  | sort xs =
    let val (ys, zs) = split xs
    in merge (sort ys, sort zs) end
```

Mergesort

The work (sequential time) is optimal, $O(n \log n)$ for *n* items.

The span (parallel time) is sensitive to the data structure:

- For lists, O(n), because splitting is slow.
- For trees, $O(\log^3 n)$, using rebalancing.

The parallelizability ratio, w/d, is $O(n/\log^2 n)$ for trees.

The correctness of the parallel implementation is never in question!
Brent's Principle: A computation with work w and span d can be implemented on a p-processor PRAM in time $O(\max(w/p, d))$.

- Work in chunks of *p* as much as possible.
- Number of processors is chosen at run-time.
- Proof is constructive: exhibits a scheduler.

Relates abstract to concrete cost.

IO Efficiency

Aggarwal and Vitter introduced the IO Model:

- Distinguish primary from secondary memory.
- Cache size $M = k \times B$ words.
- Evaluate algorithm efficiency in terms of *M* and *B*.

Main result: k-way merge sort is optimal for the IO model:

 $O(n/B \log_{M/B}(n/B))$

IO Efficiency

A&V's results can be matched in a purely functional model.

- No manual memory management.
- Natural functional programming.

Key idea: temporal locality implies spatial locality.

- Allocation order determines proximity.
- Reloading of migrated objects preserves proximity.
- Control stack specially managed to avoid cache contention.

Cost semantics makes storage explicit:

 $\sigma @ e \Downarrow^{n} \sigma' @ v$

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- Linearly ordered allocation cache of size *M*.

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Figure of merit: traffic between main memory and cache expressed in terms of M and B.

$$\sigma (\mathfrak{o} e_1 \Downarrow^{n'_1} \sigma'_1 \mathfrak{o} l'_1)$$

$$\sigma (\mathfrak{o} \operatorname{app}(e_1; e_2) \Downarrow^{n'_1 + n''_1 + n_2 + n'_2} \sigma' \mathfrak{o} l'$$

$$\left\{\begin{array}{ccc} \sigma_1 \otimes e_1 \Downarrow^{n'_1} & \sigma'_1 \otimes l'_1 \\ \sigma'_1 \otimes l'_1 \downarrow^{n''_1} \sigma''_1 \otimes \lambda x.e & & & \\ \\ & & & \\ \hline \sigma \otimes \operatorname{app}(e_1; e_2) \Downarrow^{n'_1+n''_1+ n_2+n'_2} \sigma' \otimes l' \end{array}\right\}$$

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Thus, the cost semantics is a valid basis for IO analysis.

Merge, Revisited

```
fun merge nil ys = ys
  | merge xs nil = xs
  | merge (xs as x::xs') (ys as y::ys') =
    case compare x y of
    LESS ⇒ !a::merge xs' ys
    | GTEQ ⇒ !b::merge xs ys'
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Merge, Revisited

A data structure is compact iff it may be traversed in time O(n/B).

Thm: For compact inputs xs and ys the call merge xs ys has cache complexity O(n/B).

- Recurs down lists allocating only stack *n* frames: O(n/B).
- Returns allocating *n* list cells: O(n/B).

Copying operations !a and !b ensure compactness (locality).

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- Sequential and parallel time [B & Greiner 96].
- Space usage of scheduling [Spoonhower, B, Gibbons, & H 09].
- Memory hierarchy effects [B& H 13, 15].

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Cost semantics integrates the combinatorial aspects:

- Enrich the tools available to algorithms designers.
- Extend complexity analysis to mathematically elegant languages.

Develop new (abstract and concrete) cost measures.

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Improve both the structure and efficiency of programs!

References



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